

**Chapter
3**

Vectors and Scalars

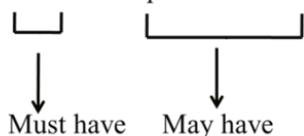
Day - 1

VECTOR AND SCALARS

Physical Quantity

May have numerical value, units and any specified direction.

Physical quantity = n u + specified direction



Magnitude of any quantity = n u

↓ ↓

Numerical Units

Value

Note:- Some physical quantities only having numerical value not specified direction.

Ex:- Refractive index, strain etc.

We can say any physical quantity Must/may have numerical value(n), unit (u) and specified direction.

PHYSICAL QUANTITY (N + U + DIRECTION) MAY/MUST HAVE

Scalars	Vectors	Tensors
“This type of physical quantities never required any specified direction” “But it may have direction Ex: Electric current (Scalar quantity) 10 Å Ex:-Electric current (scalar quantity) (n + u direction) “ on addition, subtraction and product we do not need to follow any specified rules or Laws” Example: Distance, speed, time mass volume, All types of energies work done, Electric or magnetic flux, temperature etc.	“ this types of physical quantities must have/ required any specified direction” “ on addition, subtraction and product we must have to follow certain laws or rules” Ex:- For addition or subtraction is law of parallelogram. For product = dot or cross products Example:- Displacement, velocity All types of fields intensities, force torque, momentum etc.	“ This type of physical quantities have no specified direction but different values in different direction” Ex:- Moment of inertia refractive index stress, strain etc.

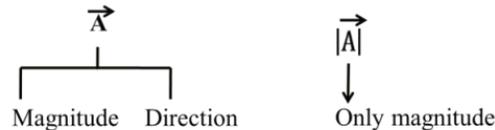
Vectors and Scalars

Note:

Scalars or zero order tensors: Any physical quantity have only one component.

Vectors or first order tensors: Any physical Quantity have component greater then one but less than or equal to four.

REPRESENTATION OF VECTOR:



Types of vectors

(1) Polar Vectors:

Vectors related to linear motion of any object Ex. Displacement, velocity, Force etc.

(2) Axial vectors:

Vector represent rotational effect and are always along the axis of rotation Ex: Angular velocity, torque, angular momentum etc.

(3) Null vector or zero vectors:

Vector whose magnitude is zero and direction is determinant.

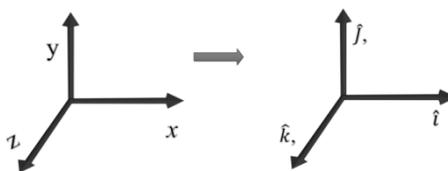
(4) Unit vectors:

Vector having magnitude equals to one (unity) but must be some specified direction representation of unit vector – , \hat{A}

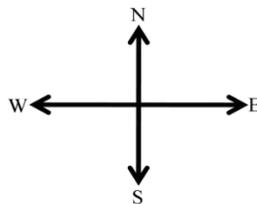
$$\hat{A} = \frac{\vec{A}}{|\vec{A}|}$$

STANDARD UNIT VECTOR

These are \hat{i} , \hat{j} , \hat{k} ,



Direction should be on your copy

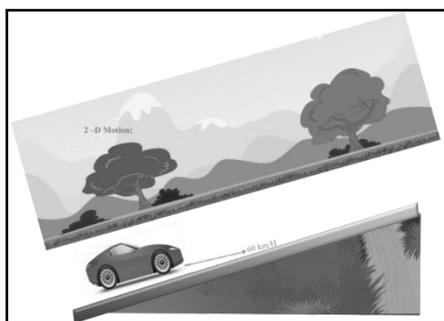
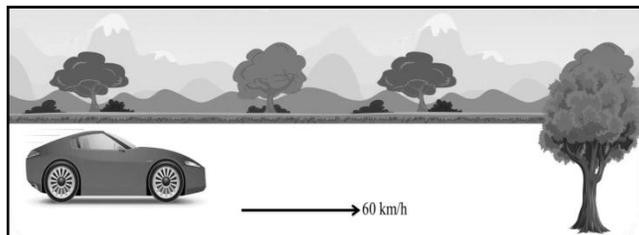


UNDERSTANDING OF UNIT VECTORS

1 –D Motion: Motion along x or y or z

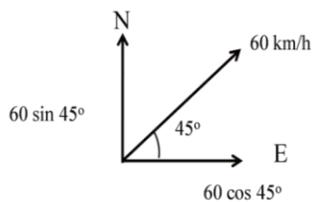
A car is moving with 60 k/m toward or due east then speed (scalar) = 60 km/h

Velocity (Vector) = 60 km/h



2 –D Motion:

A car is moving with 60 k/m due north – east then



$$\vec{V}_{car} = (60 \cos 45^\circ)\hat{i} + (60 \sin 45^\circ)\hat{j}$$

$$= \left(\frac{60}{\sqrt{2}}\hat{i} + \frac{60}{\sqrt{2}}\hat{j}\right) k/h$$

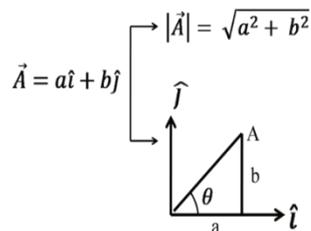
2 –D vector

$$\tan \theta' = \frac{b}{a} = \frac{\text{coeff.of } \hat{j}}{\text{coeff.of } \hat{i}}$$

With x axis or with horizontal

$$\tan \theta = \frac{a}{b} = \frac{\text{coeff.of } \hat{i}}{\text{coeff.of } \hat{j}}$$

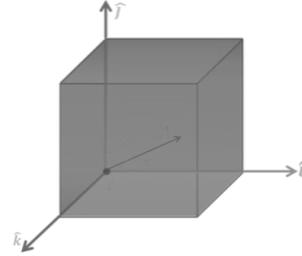
With Y -axis or with vertical



3-D Vector

$$\text{if } \vec{A} = a\hat{i} + b\hat{j} + c\hat{k}$$

$$|\vec{A}| = \sqrt{a^2 + b^2 + c^2}$$



DIRECTION

$$\cos \alpha = \frac{a}{\sqrt{a^2 + b^2 + c^2}}$$

With x-axis

$$\cos \beta = \frac{b}{\sqrt{a^2 + b^2 + c^2}}$$

With y-axis

$$\cos \gamma = \frac{c}{\sqrt{a^2 + b^2 + c^2}}$$

With z-axis

ADDITION AND SUBTRACTION OF VECTORS

Law of parallelogram

$$\text{Let } \vec{R} = \vec{P} \pm \vec{Q}$$

Here \vec{P} and \vec{Q} are two vector to be added or subtracted and \vec{R} is resultant vector.

Now magnitude of resultant \vec{R}

$$R^2 = P^2 + Q^2 \pm 2PQ \cos \alpha \text{ here } \alpha \text{ is angle between } \vec{P} \text{ and } \vec{Q}$$

For $R_{\max} \rightarrow \alpha = 0^\circ, \vec{P} \uparrow \vec{Q}$ (Parallel)

$$\text{Then } R_{\max} = P + Q$$

For $R_{\min} \rightarrow \alpha = 180^\circ, \vec{P} \downarrow \vec{Q}$ (Anti parallel)

$$\text{Then } R_{\min} = P - Q$$

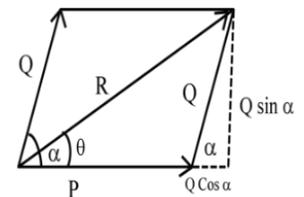
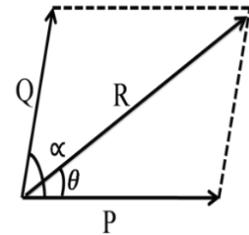
Similarly if $\alpha = 90^\circ, P \perp Q$ (Perpendicular)

$$R = \sqrt{P^2 + Q^2}$$

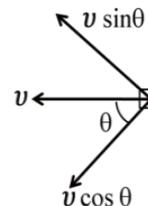
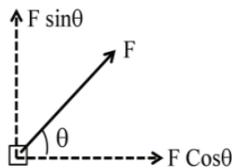
Direction of resultant vector \vec{R}

Angle of \vec{R} with horizontal (or with \vec{P})

$$\tan \theta = \frac{Q \sin \alpha}{P + Q \cos \alpha}$$



RESOLVING OF ANY VECTOR



Example. Two equal vector have a resultant equal to either of the two. The angle between them is

Vectors and Scalars

- (a) 90° (b) 60°
 (c) 120° (d) 0°

Solution: By using expression $R^2 = P^2 + Q^2 + 2PQ \cos \alpha$

Let $|R| = |P||Q| = x$ then $x^2 + x^2 + 2x \cdot x \cos \alpha$

$$x^2 = 2x^2 (1 + \cos \alpha)$$

$$\frac{1}{2} = 1 + \cos \alpha$$

$$\cos \alpha = -1/2 = \alpha = 120^\circ$$

Answer is (c)

Example: Two vector having equal magnitude of x units acting at an angle of 45° have resultant $\sqrt{(2) + \sqrt{2}}$ units the value of x is

- (a) 0 (b) 1
 (c) $\sqrt{2}$ (d) $2\sqrt{2}$

Solution: Using the expression $R^2 = P^2 + Q^2 + 2PQ \cos \alpha$

Here $|\vec{P}| = |\vec{Q}| = x$, $|\vec{R}| = \sqrt{2 + \sqrt{2}}$, $x = 45$

$$(\sqrt{2 + \sqrt{2}})^2 = x^2 + x^2 + 2x \cdot x \cos 45^\circ$$

$$(2 + \sqrt{2}) = 2x^2 + 2x^2 \cos 45^\circ$$

$$(2 + \sqrt{2}) = 2x^2 + \sqrt{2} x^2$$

$$(2 + \sqrt{2}) = x^2(2 + \sqrt{2})$$

$$\Rightarrow x^2 = 1$$

Ans (b) $\Rightarrow x = 1$ Ans (b)

Example: If $|\vec{P} + \vec{Q}| = |\vec{P} - \vec{Q}|$ find the angle between \vec{P} and \vec{Q}

- (a) 0° (b) 180°
 (c) 90° (d) 120°

Solution: As given $|\vec{P} + \vec{Q}| = |\vec{P} - \vec{Q}|$

$$\sqrt{P^2 + Q^2 + 2PQ \cos \theta} = \sqrt{P^2 + Q^2 - 2PQ \cos \theta}$$

$$= 4PQ \cos \theta = 0$$

$$\cos \theta = 0$$

$$\theta = 90^\circ$$

Answer is (c)